

# ELECTROHYDRAULIC THRUSTERS

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CATALOG OF DEVICES





**Fluidotehnic d.o.o.**  
**Serbia**

36210 Vrnjacka Banja  
Rudjinci 175/A

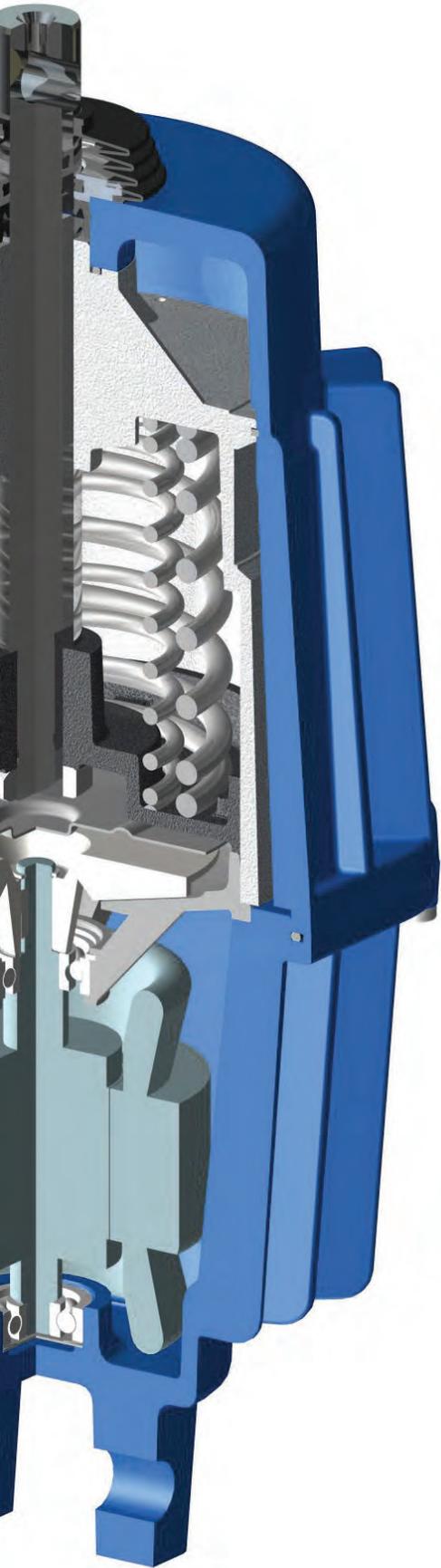
**Tel:** +381-(0)36-631-710  
+381-(0)36-631-711

**Fax:** +381-(0)36-631-712

**[www.fluidotehnic.com](http://www.fluidotehnic.com)**  
**[office@fluidotehnic.com](mailto:office@fluidotehnic.com)**



# SERIES "ESM"



Easy installation and deinstallation

Short actuating times

High operational safety

Ability to work from  $-45^{\circ}\text{C}$  to  $+70^{\circ}\text{C}$

Standard version 2000c/h or ED100% (S1)



Different voltages and frequencies  
of electric power



Standard mechanical protection IP66



Resistance to heavy duty



External controllers of device



Internal controllers of device

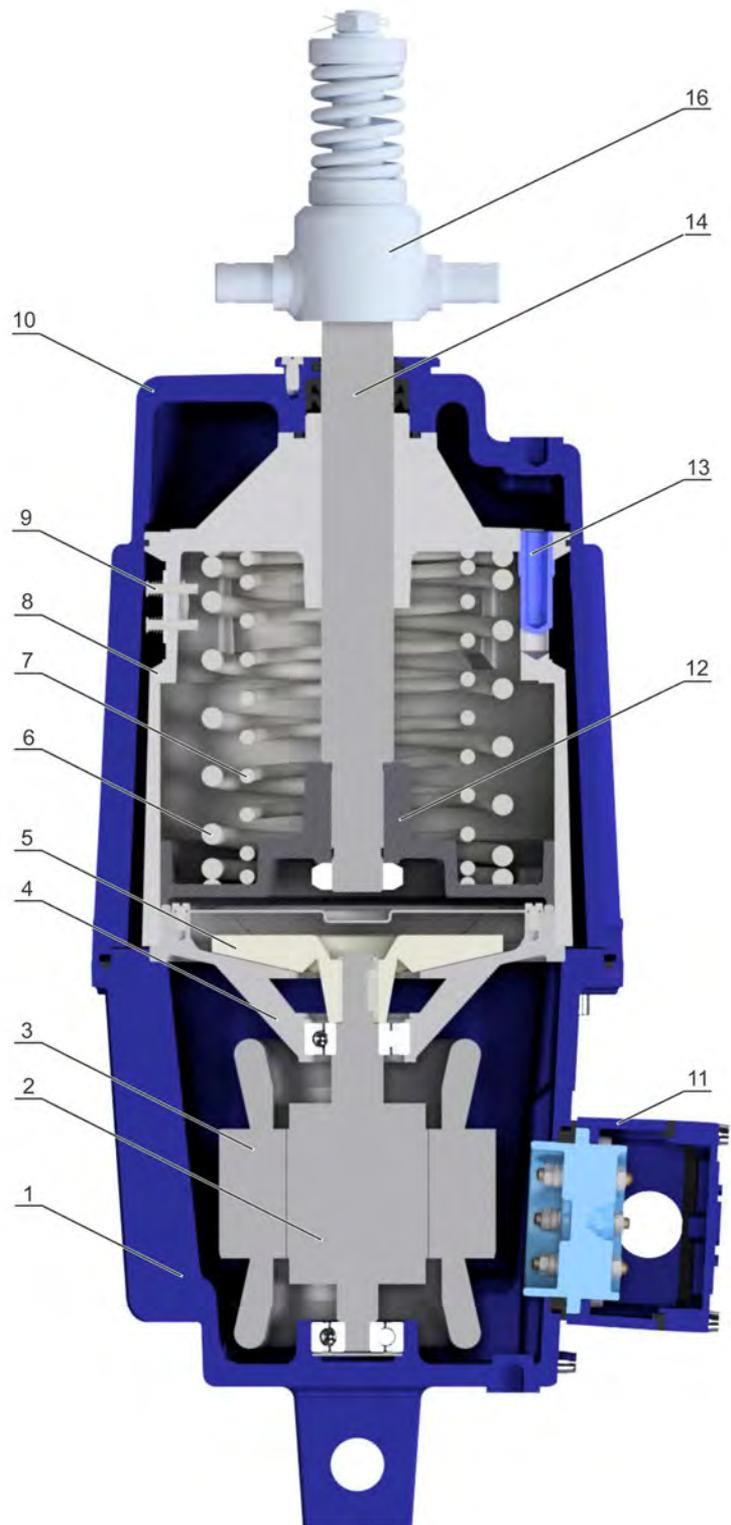


## TECHNICAL DESCRIPTION OF THE DEVICE

Housing of the motor **(1)** is constructed with eyelet connection and can be fixed on fundament by a bolt. There is also oil drain plug on the housing. Driving motor stator **(3)** (squirrel cage asynchronous motor) is fitted in the housing. Connecting box for electrical supply **(11)** is fixed on the housing hermetically separated from the inside of the housing. The rotor **(2)** is fixed in the housing by its downside, and upside fitted in the turbine bearing **(4)**. The turbine wheel **(5)** is mounted on the rotor shaft. The guide cylinder **(8)** with piston **(12)** and rod **(14)** is located upper the turbine.

In the guide cylinder is also screw **(13)** for adjusting speed of the rod. On the upper side the guide cylinder is covered by upper housing **(10)**, which with the motor housing forms a functional entirety.

The transformer oil fills interior of the device. The electric motor drives the turbine, which produce oil pressure downside of the piston. The piston and the rod are forced to move upward. The oil from upside of the piston returns through the holes to the turbine inlet. Hydraulic force is completely independent of the piston position, it depends only of the speed of turbine (current frequency), turbine size, and of the piston diameter. When lifting, motion is uniformly in the range of nominal force, independent of the load.

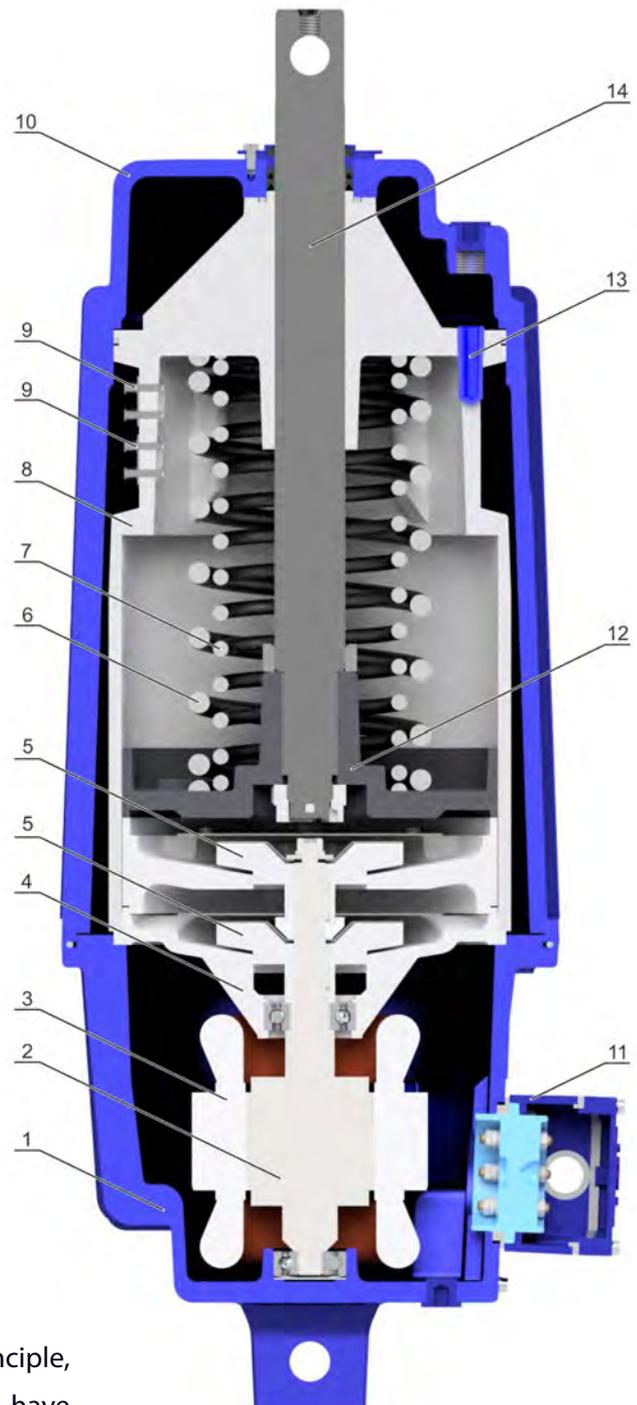


Pushing force gradually increase during 0.1 – 0.15 s, which provide very soft start of the rod. Electric motor has excellent cooling since transformer oil transfers heat to device housing and over the fins is transferred to the environment.

This device construction provides a constant output force, regardless of the position of the piston rod and the possibility of continuous operation without overloading. Switching off the electric motor, outside load caused the backward movement. Oil under the piston is suppressed back through the circuit of the turbine and through the corresponding holes exceeds into the zone above the piston. Oil level in device should be on the down blade of the filling port on upper housing **(10)** (device is in the vertical position). In the case of recharge, previously removed regulating screw **(13)**.

Any position of the rod could be chosen for the output position. This is very important for brake releasing application, because thus compensate for brake linings wear. It is recommended that the brake should be adjusted (when it is completely closed) for 1/3 stroke of the rod.

Constructive, all sizes based on the same principle, except ESM-320, which, due required pushing force, have twostage turbine circuit. Thus was obtained the required pushing force from the device which has the same external dimensions like ESM-250.



*According to the customer request, several versions also available:*

**Device with return springs C (6,7)**

One or two springs are mounted upper the piston. The piston forced back to the start position by the spring, after the motor switching off. There are three versions of the device, depends of the spring force: internal, external and both of them. It should be considered that the spring force reduces the nominal output force. The nominal return spring force is given according to the piston position on the 1/3 stroke. In full extract position of the rod, real return force exceeds nominal value for approximately 20%, in full retract position, pushing force is reduced for 10%.

**Device with shock absorber R (16)**

The shock absorber, fixed on the rod, prevents starting and stopping shocks and enables swiveling of the brake mechanism around the rod axe and around the perpendicular axe. This provides gradual increasing of the braking force up to a maximum.

**Device with speed control valve (9)**

The speed control valve is build on the cylinder holes and, depends of the type, prevent the one of the flow directions. There are few types of speed controls valves:

**Check valve for the lifting speed control - H.**

In case of the piston movement to the upper position, check valve is closed so the flow is enabling only through the port beside the adjustment screw **(13)**. Then the speed is determined by the screw position. When the piston moves down, the check valve is opened and speed is maximal. Turning the adjustment screw in clockwise direction produces lower, counter clockwise higher speed. Before the adjusting it is necessary to remove the socket screw for filling.



### Check valve for the lowering speed control - S.

The function of the valve is opposite as already described, the downward speed is determined by the screw position.

### Throttle valve for the speed control in the both directions - D.

The flow is restricted in the both of the directions and it always depends of the adjustment screw position.

*It should be considered that these valves reduce speed of the device. If the maximum speed is necessary, the valves should not be used!*



### Device with cover protection (15)

The cover protects the rod and seal set from dust penetration. It allows long life of the device in heavy operating conditions (surface minings and cement industry).

### Working signalisation of the device

- Device with external mechanical switch **Im** and **Im1** (brake open, linings worn)
- Device with inside mechanical switch **MP** (brake open)
- Device with external inductive switch **In** and **In1** (brake open, linings worn)
- Device with inside magnet-inductive switch **Lk2** and **Lk4** (brake open, linings worn)

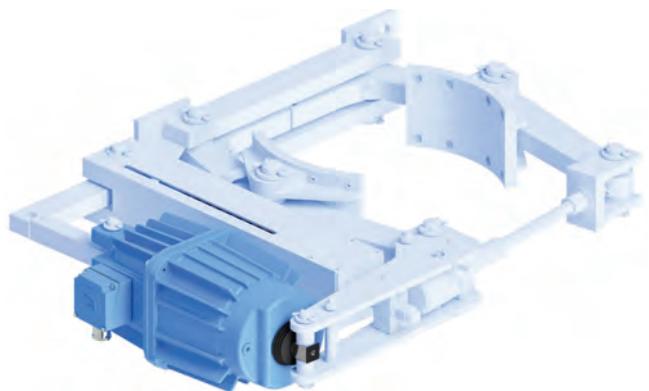
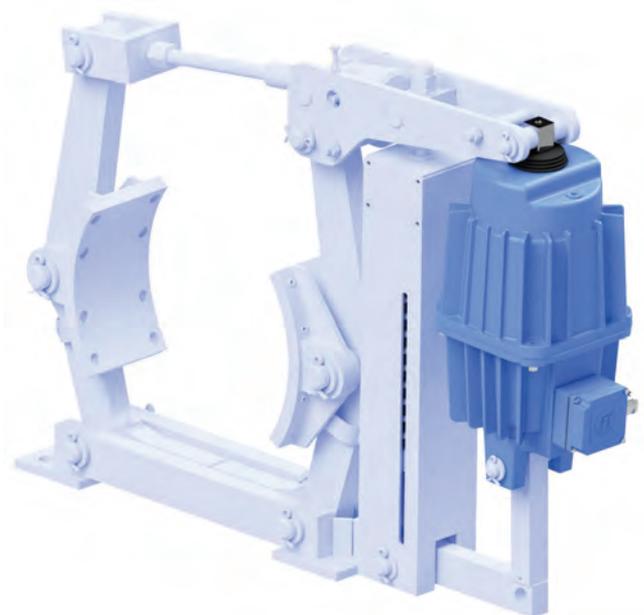
We meet the special customer requests for voltage and frequency. For extremely hard operation conditions, such as permanent operation under tropic temperature, or for the periodical operation under extremely low temperature, we used special seals, electric motors and adequate synthetically oils. To choice the best solution, we recommend to contact our experts.

## VARIANTS OF INSTALLATION

The device is possible to use in vertical, horizontal (lifting rod in horizontal position  $\pm 30^\circ$ ) or inverted position. In the vertical position, installation and operation are easiest. In the horizontal and inverted positions, the device may be installed so that the terminal box will be located at the side, provided the symbol „ II “ was added after the type designation in the order. If in the horizontal service position space considerations require to mount the terminal box either on top or on the bottom, a modification of the device is required and has to be carried out by a specialist. When ordering this version, the symbol „ I “ must be added after the type designation. If the devices are to be used in an inverted position (lifting rod vertically downwards  $\pm 60^\circ$ ), consultation with manufacturer is necessary.



**VARIANT "II"**



**EXAMPLES FOR VARIANT "II"**

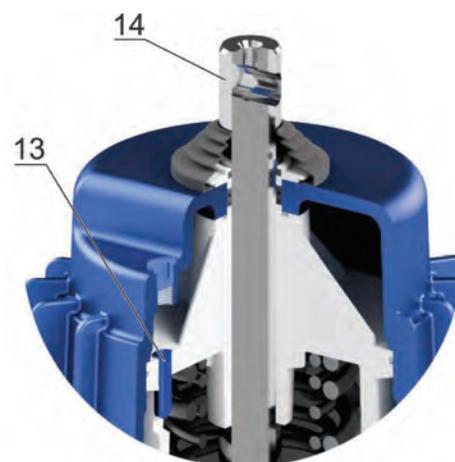


**EXAMPLE FOR VARIANT "I"**

The point is that, when installing the device in a horizontal position, the plane in which the piston rod **(14)** and the control bolt **(13)** are located are horizontal. In this way, the device will work properly and have adequate technical characteristics.



**VARIANT "I"**



The delivered device is filled with oil and prepared for installation. Device is fixed using a bolt that goes through eyelets of the lower housing and another bolt through rod. If the shock absorber is built on the device, there is the fork for the upper connection. Design of a mechanism to which is connected the device should be such that prevent rod load with lateral forces during operation. Since the turbine is symmetrical, the direction of rotation of electric motors is not important for device function.

TECHNICAL CHARACTERISTICS OF DEVICES

Size	Type	Nom. stroke	Nominal pushing force	Nominal return force	Power	Current	Mass without oil	Oil's mass	Lifting time	Lowering time
		mm	N	N	W	A	kg	kg	s	s
0	ESM 12/50 ESM 12/50 C12 ESM 12/50 C18 ESM 12/50 C22	50	220	0 120 180 220	200	0.35	11.6	1.4	0.45	0.4
1	ESM 20/50 ESM 20/50 C12 ESM 20/50 C20	50	300	0 120 200	150	0.5	9.5	1.8	0.4	0.45
2	ESM 50/50 ESM 50/50 C18 ESM 50/50 C32 ESM 50/50 C50	50	500	0 180 320 500	200	0.55	12.5	2.6	0.4	0.45
2	ESM 50/60 ESM 50/60 C18 ESM 50/60 C32 ESM 50/60 C50	60	500	0 180 320 500	200	0.55	12.5	2.6	0.4	0.45
2.1	ESM 50/100 ESM 50/100 C18 ESM 50/100 C32 ESM 50/100 C50	100	500	0 130 290 420	200	0.55	14	3.2	0.8	0.7
3	ESM 80/60 ESM 80/60 C45 ESM 80/60 C80	60	800	0 450 800	350	0.6	19.7	4.3	0.45	0.5
3.1	ESM 80/160 ESM 80/160 C45 ESM 80/160 C80	160	800	0 300 520	350	0.6	22	6	1.0	0.9
3	ESM 125/60 ESM 125/60 C45 ESM 125/60 C80 ESM 125/60 C125	60	1250	0 450 800 1250	400	0.65	19.7	4.3	0.6	0.4
3.1	ESM 125/160 ESM 125/160 C45 ESM 125/160 C80 ESM 125/160 C125	160	1250	0 300 520 820	400	0.65	22	6	1.2	0.9
3	ESM 150/60 ESM 150/60 C45 ESM 150/60 C80 ESM 150/60 C125	60	1500	0 450 800 1250	450	0.7	19.7	4.3	0.7	0.4
3.1	ESM 150/160 ESM 150/160 C45 ESM 150/160 C80 ESM 150/160 C125	160	1500	0 300 520 820	450	0.7	22	6	1.2	0.8
4	ESM 250/60 ESM 250/60 C70 ESM 250/60 C130 ESM 250/60 C200	60	2500	0 700 1300 2000	500	0.7	31.5	9	0.65	0.45
5	ESM 250/160 ESM 250/160 C70 ESM 250/160 C130 ESM 250/160 C200	160	2500	0 510 850 1360	500	0.7	37.5	10.5	1.5	0.95
5	ESM 320/100 ESM 320/100 C70 ESM 320/100 C250* ESM 320/100 C320*	100	3200	0 580 2300 2950	600	0.9	39.5	9.5	1.1	0.7

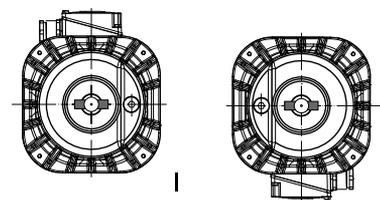
\* For the devices ESM 320/100 C250 and ESM 320/100 C320 nominal stroke of piston rod is limited to 60mm.

		Standard variant	For high temperatures		For low temperatures	
Symbol		-	T	TW06	TW07	L
Environment temperature	maximum	+40°C	+45°C	+60°C	+70°C	+40°C
	minimum	-25°C	-25°C	-10°C	-10°C	-45°C
Hydraulic fluid - oil type		Insulation oil NYNAS NYTRO 4000X			AEROSHELL FLUID 41	
Voltage and motor frequency		3 x 400V 50Hz				
Duty of device		2.000 cycles/h or ED 100% (S1)	350 cycles/h or ED 35% (S3)	250 cycles/h or ED 25% (S3)	2.000 cycles/h or ED 100% (S1)	
Mechanical protection		IP 66				
Variant on customer request	Voltage of electromotor		od 200V do 660V			
	Frequency		od 42Hz do 60Hz			
	Work control	Mechanical switch	Im	External mechanical control sensor signals that the brake is raised (open)		Voltage 24...250V AC/DC; current 2,5A; external IP65: The guaranteed activation point is max. 0,3mm from the maximum position of the activated thruster
			Im1	External mechanical control sensor signals that the brake is raised (open) and brake lining are worn		
			MP	Internal mechanical control sensor signals that the brake is raised (open)		
	Inductive switch	In	External inductive control sensor signals that the brake is raised (open)		Voltage 15...250V AC 500 mA 45...65 Hz NO/NC	
		In1	External inductive control sensor signals that the brake is raised (open) and brake lining are worn			
	Magnetic-inductive switch	Lk2	Internal control sensor signals that the brake is raised (open)		Voltage 24...250V AC/DC; current 0,5A; The guaranteed activation point is max. 5mm from the maximum position of the activated thruster	
Lk4		Internal control sensor signals that the brake is raised (open) and brake lining are worn				

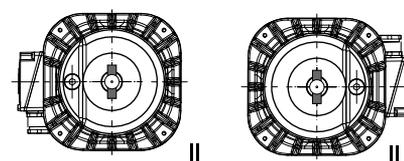
### NOTES:

- Nominal pushing force for the device without a spring, is a declared force on the piston rod in the output direction. Maximum pushing force is ~ 50% higher. In devices with spring it is reduced by force springs.
- Nominal return force is a force of the spring for returning the piston rod and this information related to the 1/3 piston rod stroke. Tolerance is ±10%.
- The weight of the device and oil are approximate (depending on additional equipment).
- Time of lifting and lowering is related to a variant of the device without irreversible valve with built-in springs, i.e. with the corresponding external load. Tolerance is ±10%. In devices with built-in non return valve min. lifting and lowering time is greater for ~ 25%, while by the wring screw (13) can be continuously adjusted up to a maximum of 3- 5s for a stroke rate 50-60mm, 8-12s for the stroke rate 100 mm and 10-15s for the stroke rate 160mm.
- Nominal power and current refer to temperature of the device 20°C. Lowering temperature causes an increase in oil viscosity, in which case the nominal value of the power and current are growing and can be up to 50% higher.

### POSITION OF TERMINAL BOX WHEN THE DEVICE WORKS IN A HORIZONTAL POSITION



Foot bolt horizontal

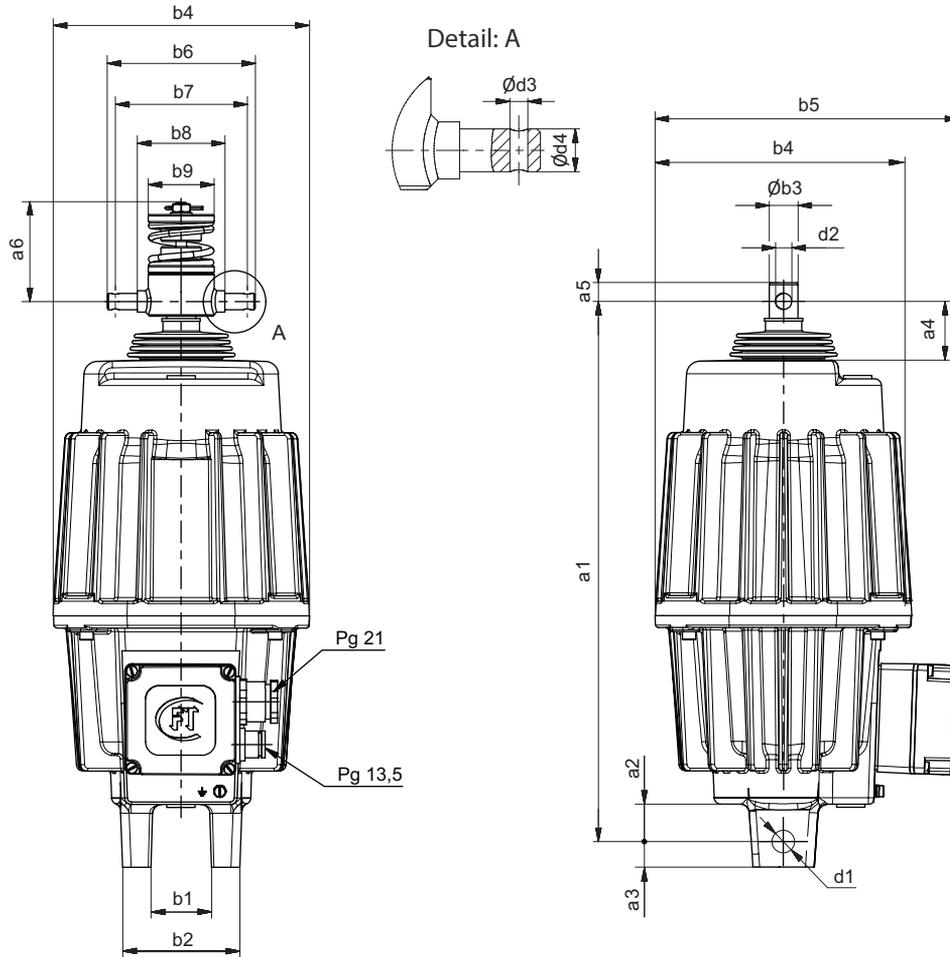


Foot bolt vertical

# INSTALLATION DRAWING

## VARIANT WITH SHOCK ABSORBER - R

## VARIANT WITHOUT SHOCK ABSORBER - R



The devices are homologated by INSTITUTE FOR QUALITY 1. MAJ – Nis, registered number is 03-3322/2 from 25.12.1996. and they are produced in accordance with the EC-safety requirements. The CERTIFICATE OF SAFETY and CERTIFICATE OF TESTING are available for each device.

DIMENSIONS SIZE	INSTALLATION DIMENSIONS:																			
	a1 <sup>±1</sup>	a2	a3 <sup>+1</sup>	a4 <sup>±1</sup>	a5	a6	b1 <sup>+2</sup>	b2 <sup>+1</sup>	b3 <sup>e8</sup>	b4	b5	b6	b7 <sup>+0,5</sup>	b8 <sup>±0,5</sup>	b9	d1 <sup>+0,1</sup>	d2 <sup>F9</sup>	d3	d4 <sup>e8</sup>	
0	286	18	15	26	12	106	40	80	20	140	209	110	98	65	49	16.1	12	5	12	
1	380	30	20	30	17	106	40	80	21.5	150	200	110	98	65	49	20.2	12	5	12	
2	400	30	20	32	17	106	40	90	21.5	180	220	110	98	65	49	20.2	12	5	12	
2.1	452	30	20	32	17	106	40	90	21.5	180	220	110	98	65	49	20.2	12	5	12	
3	458	30	25	36	21	140	40	90	27.5	208	232	110	98	65	49	20.2	16	5	16	
3.1	573	30	25	36	21	140	40	90	27.5	208	232	110	98	65	49	20.2	16	5	16	
4	549	30	25	36	25	189	40	90	35.5	250	265	120	105	70	58	20.2	20	5	20	
5	660	30	25	36	25	189	40	90	35.5	250	265	120	105	70	58	20.2	20	5	20	

## ORDER INSTRUCTION

		1	2	3	4	5	6	7	8
<b>ESM</b>	Type	1							
-	Without shock absorber		2						
<b>R</b>	With shock absorber								
-	Without valve			3					
<b>S</b>	With valve for lowering speed control								
<b>H</b>	With valve for lifting speed control								
<b>D</b>	With valve for speed control in both directions								
<b>II</b>	Service/installation position: vertical, inverted, horizontal terminal box located at the side				4				
<b>I</b>	Service/installation position horizontal terminal box at top or bottom								
-	Without cover protection					5			
<b>Z</b>	With cover protection								
-	Standard variant						6		
<b>T ; (TW)</b>	For high temperatures								
<b>L</b>	For low temperatures								
-	Standard variant								
<b>Im</b>	With external mechanical switch - brake open								
<b>Im1</b>	With external mechanical switch - brake open and brake wear lining control								
<b>In</b>	With external inductive switch - brake open							7	
<b>In1</b>	With external inductive switch - brake open and brake wear lining control								
<b>Lk2</b>	With inside magnet- inductive switch - brake open								
<b>Lk4</b>	With inside magnet- inductive switch - brake open and brake wear lining control								
<b>MP</b>	With inside mechanical switch - brake open								
	Voltage and frequency								8

**NOTES:**

Stroke indicators: *Im, In, Lk2 and MP* indicate maximum ejection of the rod (brake open).

Stroke indicators: *Im1, In1 and Lk4* indicate maximum ejection of the rod (brake open) and that the brake linings are worn (used-up).

Internal indicator is build inside of device. Current supply for indicator is provided from connecting box used cable gland Pg 13,5.

Standard execution of devices is with protection against corrosion, due to the working conditions, such as surface mines, ironworks, cement works etc. If devices are used in extremely difficult conditions (presence of acids, bases, sea water), the special variants are produced.

**EXAMPLES**

Electrohydraulic thruster with pushing force 1250N, stroke 60mm, with return spring 800N, shock absorber and valve for lowering speed control, voltage 400V 50Hz is marked:

**ESM 125/60 C80 R S 400V 50Hz**

Electrohydraulic thruster with pushing force 500N, stroke 50 mm, with return spring 500N, valve for lowering speed control, cover protection, for high temperatures, with inside sensor for control device check voltage 500V 50Hz is marked:

**ESM 50/50 C50 S Z T MP 500V 50Hz**

Electrohydraulic thruster with pushing force 2500N, stroke 160mm, without return spring, with valve for lifting speed control, for low temperature, voltage 400V 50Hz is marked:

**ESM 250/160 H L 400V 50Hz**

## ELECTROHYDRAULIC THRUSTERS SERIES ESM DIN 15430

Size	Type	Nom. stroke	Nominal pushing force	Nominal return force	Power	Current	Mass without oil	Oil's mass	Lifting time	Lowering time
		mm	N	N	W	A	kg	kg	s	s
0	ESM 120-40 ESM 120-40 C60 ESM 120-40 C120	40	120	0 60 120	200	0.35	11.6	1.4	0.25	0.25
0	ESM 220-50 ESM 220-50 C120 ESM 220-50 C180 ESM 220-50 C220	50	220	0 120 180 220	200	0.35	11.6	1.4	0.45	0.40
1	ESM 300-50 ESM 300-50 C120 ESM 300-50 C200 ESM 300-50 C270	50	300	0 120 200 270	150	0.5	9.5	1.8	0.45	0.4
2	ESM 500-60 ESM 500-60 C180 ESM 500-60 C320 ESM 500-60 C500	60	500	0 180 320 500	200	0.55	12.5	2.6	0.45	0.4
2.1	ESM 500-120 ESM 500-120 C180 ESM 500-120 C320 ESM 500-120 C500	120	500	0 132 300 432	200	0.55	14	3.2	0.80	0.60
3	ESM 800-60 ESM 800-60 C450 ESM 800-60 C800	60	800	0 450 800	350	0.6	19.7	4.3	0.45	0.50
3.1	ESM 800-120 ESM 800-120 C450 ESM 800-120 C800	120	800	0 300 520	350	0.6	22	6	0.75	0.6
3.2	ESM 1250-60 ESM 1250-60 C450 ESM 1250-60 C800 ESM 1250-60 C1250	60	1250	0 450 800 1250	400	0.65	19.7	4.3	0.55	0.4
3.3	ESM 1250-120 ESM 1250-120 C450 ESM 1250-120 C800 ESM 1250-120 C1250	120	1250	0 300 520 820	400	0.65	22	6	1	0.6
4	ESM 2000-60 ESM 2000-60 C700 ESM 2000-60 C1300 ESM 2000-60 C2000	60	2000	0 700 1300 2000	500	0.7	31.5	9	0.6	0.4
5.1	ESM 2000-120 ESM 2000-120 C700 ESM 2000-120 C1300 ESM 2000-120 C2000	120	2000	0 510 850 1360	500	0.7	37.5	10.5	1.20	0.60
5.1	ESM 2500-160 ESM 2500-160 C700 ESM 2500-160 C1300 ESM 2500-160 C2000	160	2500	0 510 850 1360	500	0.7	37.5	10.5	1.50	0.65
5	ESM 3000-60 ESM 3000-60 C700 ESM 3000-60 C2500 ESM 3000-60 C3200	60	3000	0 700 2300 2950	600	0.9	39.5	9.5	0.65	0.45
5.1	ESM 3000-120	120	3000	0	600	0.9	39.5	9.5	1.20	0.70
5.1	ESM 3200-100 ESM 3200-100 C700 ESM 3200-100 C2500* ESM 3200-100 C3200*	100	3200	0 680 2300 2950	600	0.9	39.5	9.5	1,10	0,60

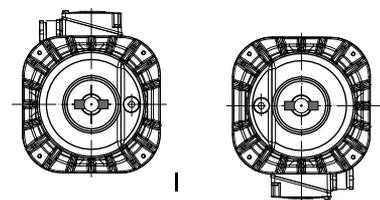
\* For the devices ESM 3200/100 C2500 and ESM 3200/100 C3200 nominal stroke of piston rod is limited to 60mm.

		Standard variant	For high temperatures		For low temperatures	
Symbol		-	T	TW06	TW07	L
Environment temperature	maximum	+40°C	+45°C	+60°C	+70°C	+40°C
	minimum	-25°C	-25°C	-10°C	-10°C	-45°C
Hydraulic fluid - oil type		Insulation oil NYNAS NYTRO 4000X			AEROSHELL FLUID 41	
Voltage and motor frequency		3 x 400V 50Hz				
Duty of device		2.000 cycles/h or ED 100% (S1)	350 cycles/h or ED 35% (S3)	250 cycles/h or ED 25% (S3)	2.000 cycles/h or ED 100% (S1)	
Mechanical protection		IP 66				
Variant on customer request	Voltage of electromotor		od 200V do 660V			
	Frequency		od 42Hz do 60Hz			
	Work control	Mechanical switch	Im	External mechanical control sensor signals that the brake is raised (open)		Voltage 24...250V AC/DC; current 2,5A; external IP65: The guaranteed activation point is max. 0,3mm from the maximum position of the activated thruster
			Im1	External mechanical control sensor signals that the brake is raised (open) and brake lining are worn		
			MP	Internal mechanical control sensor signals that the brake is raised (open)		
	Inductive switch	In	External inductive control sensor signals that the brake is raised (open)		Voltage 15...250V AC 500 mA 45...65 Hz NO/NC	
		In1	External inductive control sensor signals that the brake is raised (open) and brake lining are worn			
	Magnetic-inductive switch	Lk2	Internal control sensor signals that the brake is raised (open)		Voltage 24...250V AC/DC; current 0,5A; The guaranteed activation point is max. 5mm from the maximum position of the activated thruster	
Lk4		Internal control sensor signals that the brake is raised (open) and brake lining are worn				

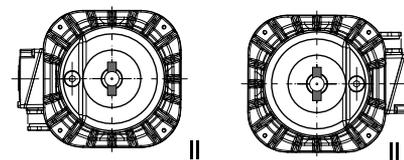
**NOTES:**

- Nominal pushing force for the device without a spring, is a declared force on the piston rod in the output direction. Maximum pushing force is ~ 50% higher. In devices with spring it is reduced by force springs.
- Nominal return force is a force of the spring for returning the piston rod and this information related to the 1/3 piston rod stroke. Tolerance is ±10%.
- The weight of the device and oil are approximate (depending on additional equipment).
- Time of lifting and lowering is related to a variant of the device without irreversible valve with built-in springs, i.e. with the corresponding external load. Tolerance is ±10%. In devices with built-in non return valve min. lifting and lowering time is greater for ~ 25%, while by the wring screw (13) can be continuously adjusted up to a maximum of 3- 5s for a stroke rate 50-60mm, 8-12s for the stroke rate 100 mm and 10-15s for the stroke rate 160mm.
- Nominal power and current refer to temperature of the device 20°C. Lowering temperature causes an increase in oil viscosity, in which case the nominal value of the power and current are growing and can be up to 50% higher.

**POSITION OF TERMINAL BOX WHEN THE DEVICE WORKS IN A HORIZONTAL POSITION**



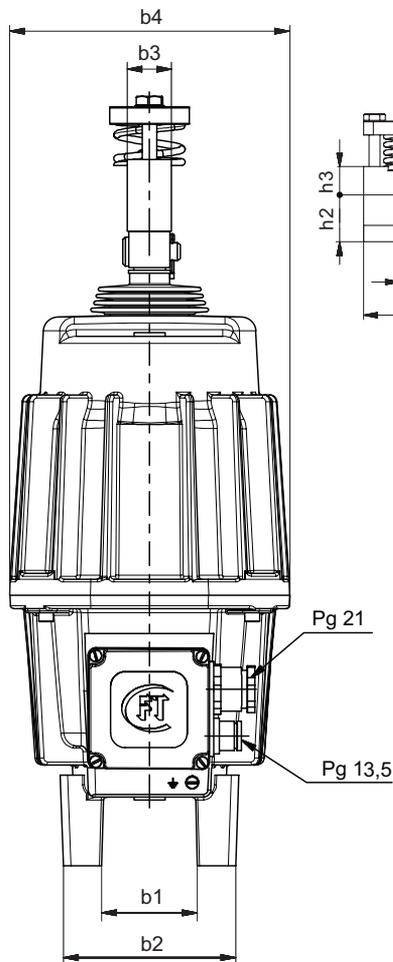
Foot bolt horizontal



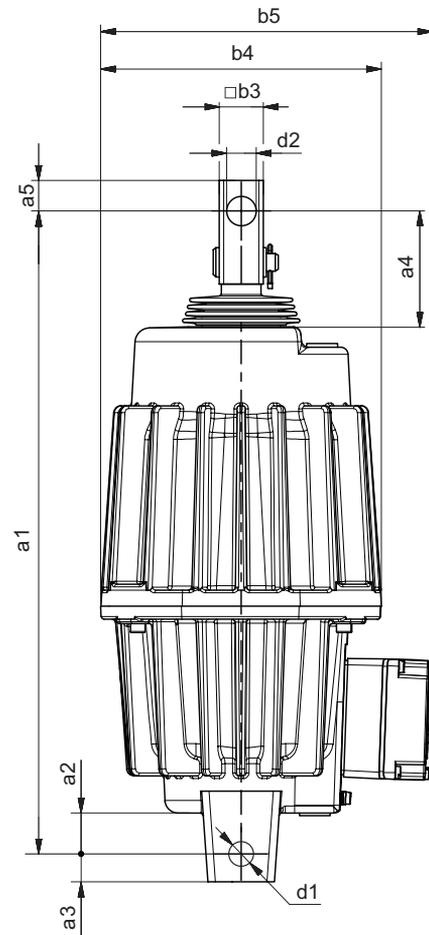
Foot bolt vertical

# INSTALLATION DRAWING

## VARIANT WITH SHOCK ABSORBER - R



## VARIANT WITHOUT SHOCK ABSORBER - R

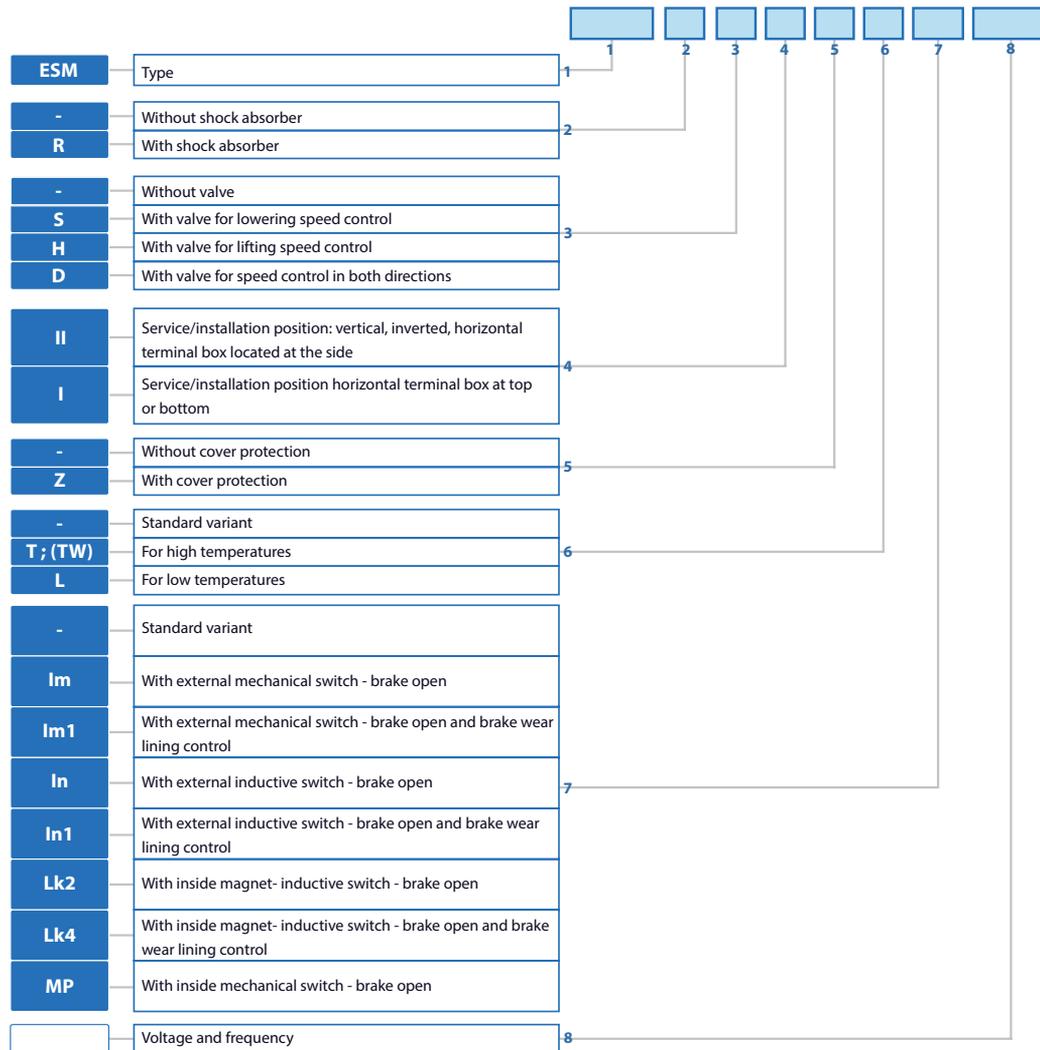


The devices are homologated by INSTITUTE FOR QUALITY 1. MAJ – Nis, registered number is 03-3322/2 from 25.12.1996. and they are produced in accordance with the EC-safety requirements.

The CERTIFICATE OF SAFETY and CERTIFICATE OF TESTING are available for each device.

DIMENSIONS SIZE	INSTALLATION DIMENSIONS:																
	a1 <sup>±1</sup>	a2	a3 <sup>+1</sup>	a4 <sup>±1</sup>	a5	b1 <sup>+2</sup>	b2 <sup>+1</sup>	b3 <sup>-0,1</sup>	b4	b5	b6	d1 <sup>+0,1</sup>	d2 <sup>F9</sup>	h1	h2	h3	h4
0	286	18	15	26	12	40	80	20	140	209	68	16.1	12	15	36	20	89
1	370	18	16	32	15	40	80	25	150	200	68	16.1	16	15	30	20	75
2	435	30	20	67	18	60	120	30	180	220	68	20.1	20	20	36	20	100
2.1	515	30	20	95	18	60	120	30	180	220	68	20.1	20	20	36	20	100
3	458	23	22	42	18	60	120	30	208	232	68	20.1	20	20	36	20	100
3.1	530	23	22	39	18	60	120	30	208	232	68	20.1	20	20	36	20	100
3.2	645	30	25	108	25	40	90	40	208	232	110	25.1	25	20	38	35	175
3.3	705	30	25	168	25	40	90	40	208	232	110	25.1	25	20	38	35	175
4	645	30	25	132	25	40	90	40	250	265	110	25.1	25	20	38	35	175
5	660	30	25	36	25	40	90	40	250	265	110	25.1	25	20	38	35	175
5.1	705	30	25	81	25	40	90	40	250	265	110	25.1	25	20	38	35	175

## ORDER INSTRUCTION



### NOTES:

Stroke indicators: *Im, In, Lk2 and MP* indicate maximum ejection of the rod (brake open).

Stroke indicators: *Im1, In1 i Lk4* indicate maximum ejection of the rod (brake open) and that the brake linings are worn (used-up).

Internal indicator is build inside of device. Current supply for indicator is provided from connecting box used cable gland Pg 13,5.

Standard execution of devices is with protection against corrosion, due to the working conditions, such as surface mines, ironworks, cement works etc. If devices are used in extremely difficult conditions (presence of acids, bases, sea water), the special variants are produced.

All devices are technologically produced in the basic version so that the customer can upgrade with valves (*H, S, D*), shock absorber (*R*), external indication (*Im, Im1, In, In1*), cover protection (*Z*).

### PRIMERI

Electrohydraulic thruster with pushing force 1250N, stroke 60mm, with return spring 800N, shock absorber and valve for lowering speed control, voltage 400V 50Hz is marked:

**ESM 1250-60 C80 R S 400V 50Hz**

Electrohydraulic thruster with pushing force 500N, stroke 60 mm, with return spring 500N, valve for lowering speed control, cover protection, for high temperatures, with inside sensor for control device check voltage 500V 50Hz is marked:

**ESM 500-60 C500 S Z T MP 500V 50Hz**

Electrohydraulic thruster with pushing force 2000N, stroke 120mm, without return spring, with valve for lifting speed control, for low temperature, voltage 400V 50Hz is marked:

**ESM 2000-120 H L 400V 50Hz**

**External mechanical switch  
"Im" and "Im1"**



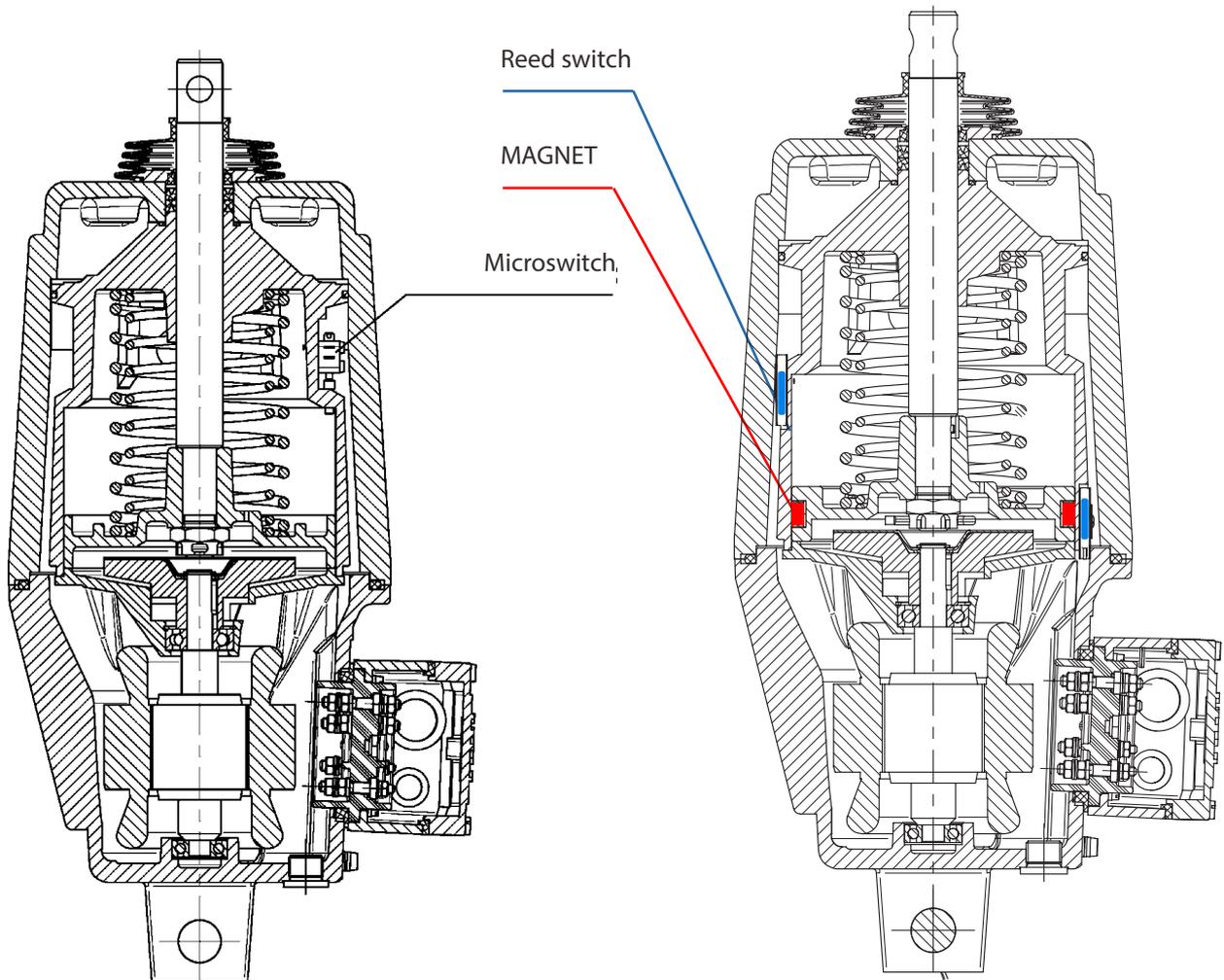
**External inductive switch  
"In" and "In1"**



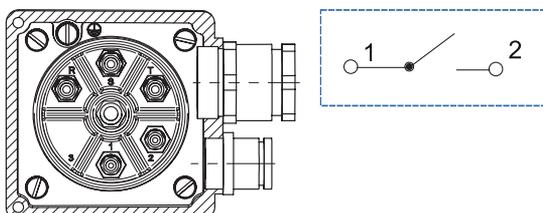
Microswitch is built on the outside of cylinder. It is activated when the piston is in the top position. In a magnetic inductive switch, switches are also built on the outside of the cylinder and activate them a permanent magnet built in the piston. The advantage of this solution is that the switches are fully protected from external influences and in this way are very reliable in the work. Linkage is done in connecting box.

**Internal mechanical switch  
"MP"**

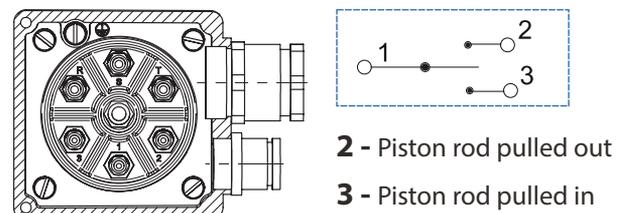
**Internal magnet-inductive switch  
"Lk2" and "Lk4"**



**Connecting box for device  
variant "MP" and "Lk2"**



**Connecting box for  
device variant "Lk4"**





SERBIA  
36210 VRNJACKA BANJA  
Rudjinci 175/A  
tel/fax: +381-36-631-710  
E-mail: office@fluidotehnic.com  
Web: www.fluidotehnic.com

Matični broj: 06568939  
Šifra delatnosti: 2822  
PIB: 100918689  
Reg. broj: 11506568939  
Br. Reg. Upisa: 1-14429-00



## EC DECLARATION OF CONFORMITY / DECLARATION ON INSTALLATION

DEKLARACIJA O USAGLAŠENOSTI / DEKLARACIJA O UGRADNJI

**We hereby declare that the following product**

Izjavljujemo da su sledeći uređaji

**ELECTROHYDRAULIC THRUSTER**

ELEKTROHIDRAULIČNI PODIZAČI

**ESM 12/50...ESM320/100 ; ESM 120-40...ESM 3200-100**

**F-EB 12/50...F-EB 320/100 ; F-EB 120-40...F-EB 3200-100**

**F-BL-12 ... F-BL-320**

**F-EHT-12.5-50 ... F-EHT-250-60 ; F-EHT-338 ... F-EHT-2960**

**F-SZH 45/50 ... F-SZH 185/120**

**F-TGM 25 ... F-TGM 50**

**F-R 12/5 ... F-REH 320/120 N5H**

**F-Ed 12/4.1 ... F-Ed 301/12.1**

**Are designed and produced in accordance with the safety requirements according to the following regulations:**

Projektovani i proizvedeni u skladu sa bezbednosnim zahtevima prema sledećim propisima:

**Machinery Directive EC/2006/42**

(Mašinska direktiva EC/2006/42)

**Low voltage directive EC/2014/35**

(Niskonaponska direktiva EC/2014/35)

**in accordance with the following standards:**

i u skladu sa sledećim standardima:

**Safety of machinery - General principles for design**

- **Risk assessment and risk reduction EN ISO 12100:2010**

Bezbednost mašina - Opšti principi za projektovanje

- Ocena rizika i smanjenje rizika SRPS ISO 12100:2014

**Safety of machinery - Electrical equipment of machines - Part 1: EN 60204-1:2016**

Bezbednost mašina - Električna oprema mašina - Deo 1: EN 60204-1:2016

**Declaration on installation in the sense of EC Machinery Directive (2006/42/EC) Annex II B**

Izjava o ugradnji u skladu sa EC Mašinskom direktivom (2006/42/EC) Anex II B

**Electrohydraulic thrusters of "FLUIDOTEHNIC" assemble into mechanical devices and equipment. Start-up is not admissible unless it has been verified that the whole equipment, meets the requirements defined in the EC machinery Directive (2006/42/EC)**

Elektrohidraulični podizači "FLUIDOTEHNIC"-a se ugrađuju u drugu opremu i dodatne uređaje. Pokretanje nije dozvoljeno sve dok i relevantna oprema u koju se ugrađuju ne bude u skladu sa Mašinskom direktivom (2006/42/EC)

**The manufacturer undertakes to supply the relevant information of incomplete machine on request to responsible inspector by electronic way. Technical documents of the machine is prepared in accordance with Annex VII, part B Machinery Directive (2006/42/EC)**

Proizvođač se obavezuje da će elektronskim putem dostaviti odgovarajuće podatke o delimično završenoj mašini nadležnom inspektor na njegov zahtev. Tehnička dokumentacija je izrađena u skladu sa Anexom 7, deo B Mašinske direktive.

Vrnjačka Banja, 01/02/2017 godine



Šljivić Miroslav, General Manager

The EC Declaration of Conformity is only valid in conjunction with confirmation that the device has been correctly applied, installed, inspected and maintained according to the operating instructions provided. The validity of the declaration will cease in case of any modification and/or supplement not previously approved by "FLUIDOTEHNIC".

Ova deklaracija o usaglašenosti važi samo u slučaju da je uređaj pravilno ugrađen, iskontrolisan i da se koristi i održava u skladu sa uputstvom za rukovanje i održavanje. Važenje izjave prestaje u slučaju bilo kakve modifikacije ili dodatka koji nisu prethodno odobreni od "FLUIDOTEHNIC"-a.



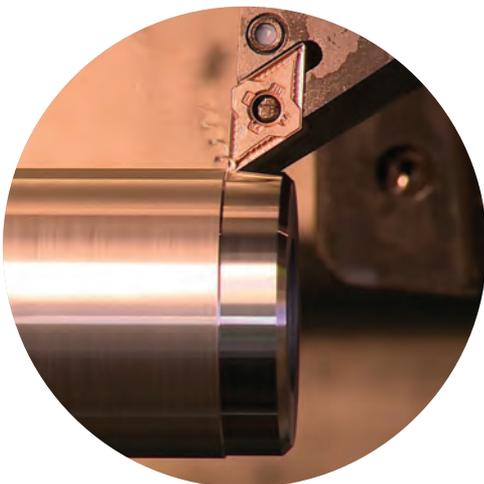


- FLUIDOTEHNIC's production program is based on its own development. Thanks to that, all the products are the result of the engineering staff work, as well as the quality and skilled workers in manufacturing and installation. Each serial product during the conquest passes through the phase of prototype development, functional tests and check in real operating conditions. Following step is removal of all possible defects and then, based on that, test series is produced. This is how we achieve high quality of manufactured devices. In case of the individual production, after the functional testing, we deliver the product to the customer.
- Since its foundation FLUIDOTEHNIC Ltd. has been continuously investing both in the expansion of commercial building and the purchase of modern equipment for the production, control and techno-economic support. It is located in the industrial zone of Vrnjacka Banja, on a lot size ~ 2ha. It consists several buildings, connected into a functional whole area of 4000 m2. The whole complex is adjusted to the environment- we are taking good care of health, work safety and environmental protection.





- Market research, device development, technical assistance and personnel training free of charge for all our customers is the main task of this service. Many years of experience in the development tasks of hydraulics, pneumatics and lubrication techniques, as well as the latest computer technology guarantee that our customers will get the optimum technical solution. During the development, every device passes precisely defined procedure, starting from making the design concept, followed by manufacturing and testing prototypes and going into production.
- It consists of several facilities and departments: foundry of non-ferrous metals, mechanical drive, locksmith department, installation and technical control. All operations from the casting to the final machining are performed with the universal and software machines. Control and assembly is 100%. When the assembly is finished, each device is being tested on the test stand and on the basis of the results it gets the appropriate certificates and guarantees. On each call of the user, service teams come in as soon as possible, with spare parts and the necessary tools, regardless of whether the equipment is in warranty or out of warranty period.



**Fluidotehnic d.o.o.**

**Serbia**

36210 Vrnjacka Banja

Rudjinci 175/A

**Tel:** +381-(0)36-631-710

+381-(0)36-631-711

**Fax:** +381-(0)36-631-712

**[www.fluidotehnic.com](http://www.fluidotehnic.com)**

[office@fluidotehnic.com](mailto:office@fluidotehnic.com)

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**02/2018**